

Brushless DC-Servomotors

with integrated Speed Controller 4 Pole Technology

58 mNm

For combination with Gearheads: 30/1, 32A, 32ALN, 32/3 (S), 38/1(S), 38/2(S)

Series 3268 ... BX4 SCDC

		3268 G		024 BX4	SCDC
1	Nominal voltage	UN		24	Volt
2	Terminal resistance, phase-phase	R		1,45	Ω
3	Output power ¹⁾	P2 max.		32,7	W
4	Efficiency	η max.		79,5	%
	,	•			
5	No-load speed	no		5 300	rpm
6	No-load current	lo		0,210	Å
7	Stall torque	Мн		137	mNm
8	Friction torque, static	Co		1,7	mNm
9	Friction torque, dynamic	Cv		1,3 ·10 ⁻³	mNm/rpm
					•
10	Speed constant	kn		220	rpm/V
11	Back-EMF constant	ke		4,555	mV/rpm
12	Torque constant	kм		43,5	mNm/A
13	Current constant	kı		0,0230	A/mNm
14	Slope of n-M curve	Δn/ΔM		7,3	rpm/mNm
15	Terminal inductance, phase-phase	L		110	μH
16	Mechanical time constant	au m		4,6	ms
17	Rotor inertia	J		60	gcm ²
18	Angular acceleration	lpha max.		23	$\cdot 10^3$ rad/s ²
19	Thermal resistance	Rth 1 / Rth 2	1,9 / 9,6		K/W
20	Thermal time constant	au w1 / $ au$ w2	17 / 1 060		s
21	Operating temperature range		- 40 + 85		°C
22	Shaft bearings		ball bearings, preloaded		
23	Shaft load max.:		2 · 1		
	- radial at 3 000 rpm (4,5 mm from mounting flange)		50		N
	– axial at 3 000 rpm		5		N
	 axial at standstill 		50		N
24	Shaft play:				
	– radial	\leq	0,015		mm
	– axial	=	0		mm
25	Housing material		stainless steel		
26	Weight		305		g
27	Direction of rotation		electronically reversible		
28	Number of pole pairs		2		
Rec	commended values - mathematically indeper	ident of eacl	n other		
29	Speed up to	Ne max.		6 500	rpm
30	Torque up to ^{1) 2)}	Me max.		37 / 58	mNm
31	Current up to ^{1) 2)}	le max.		1,11 / 1,60	А

¹⁾ at 5000 rpm

²⁾ thermal resistance Rth 2 not reduced / thermal resistance Rth 2 by 55% reduced

Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22° C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ($R_{th} \ge 55\%$ reduced).

The motor is factory pre-configured to perform at the recommended continuous current. Non-standard configurations are only possible upon request from the manufacturer.

The nominal voltage (UN) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.





Dimensional drawing



Speed Controller		024 BX4	SCDC
Power supply electronic	Up	6,5 30	V DC
Power supply motor	Umot	6,5 30	V DC
PWM switching frequency	fpwм	96	kHz
Efficiency	η	95	%
Max. continuous output current 1)	ldauer	1,6	А
Max. peak output current	Imax	4	А
Total standby current at UN	lel	10	mA
Speed range, electronics		400 50 000 ²⁾	rpm
Scanning rate		500	μs

¹⁾ at 22°C ambient temperature

²⁾ speed is dependent on the motor operating voltage

Connection Information Connection 1 "Mot +": positive power supply Connection 2 "Mot -": negative power supply

Features

In this version, the brushless DC servomotors have an integrated Speed Controller. The motor is commutated using the integrated digital hall sensors. Speed control is via a PI regulator.

The Speed Controller has a current limiting device which limits the maximum motor current if the thermal load is too high. Twice the continuous current is possible over a short time. The direction of rotation is dependent on the polarity of the voltage.

Full product description

Examples:

3268G024BX4 SCDC



