

# DC-Micromotors

## Graphite Commutation

### 5,1 mNm

For combination with  
Gearheads:  
15/10, 16/7, 17/1, 20/1  
Encoders:  
IE2-1024, IE2-16

## Series 1727 ... C

Values at 22°C and nominal voltage		1727 U	006 C	012 C	024 C	
1	Nominal voltage	$U_N$	6	12	24	V
2	Terminal resistance	R	3	13,8	57,6	$\Omega$
3	Output power	$P_{2nom.}$	2,37	2,25	2,25	W
4	Efficiency, max.	$\eta_{max.}$	70	70	70	%
5	No-load speed	$n_0$	7 800	7 800	7 800	rpm
6	No-load current, typ. (with shaft $\varnothing$ 2 mm)	$I_0$	0,055	0,026	0,013	A
7	Stall torque	$M_H$	11,6	11	11	mNm
8	Friction torque	$M_R$	0,36	0,35	0,36	mNm
9	Speed constant	$k_n$	1 460	700	343	rpm/V
10	Back-EMF constant	$k_E$	0,684	1,43	2,92	mV/rpm
11	Torque constant	$k_M$	6,53	13,6	27,9	mNm/A
12	Current constant	$k_I$	0,153	0,073	0,036	A/mNm
13	Slope of n-M curve	$\Delta n/\Delta M$	672	709	709	rpm/mNm
14	Rotor inductance	L	80	320	1 440	$\mu H$
15	Mechanical time constant	$\tau_m$	9	9	9	ms
16	Rotor inertia	J	1,3	1,2	1,2	gcm <sup>2</sup>
17	Angular acceleration	$\alpha_{max.}$	91	91	91	$\cdot 10^3 \text{rad/s}^2$
18	Thermal resistance	$R_{th1} / R_{th2}$	5 / 24			K/W
19	Thermal time constant	$\tau_{w1} / \tau_{w2}$	4,2 / 254			s
20	Operating temperature range:					
	– motor		-30 ... +100			°C
	– winding, max. permissible		+125			°C
21	Shaft bearings		ball bearings, preloaded			
22	Shaft load max.:					
	– with shaft diameter		2			mm
	– radial at 3 000 rpm (3 mm from bearing)		8			N
	– axial at 3 000 rpm		0,8			N
	– axial at standstill		10			N
23	Shaft play					
	– radial	$\leq$	0,015			mm
	– axial	$=$	0			mm
24	Housing material		steel, black coated			
25	Mass		28			g
26	Direction of rotation		clockwise, viewed from the front face			
27	Speed up to	$n_{max.}$	9 000			rpm
28	Number of pole pairs		1			
29	Magnet material		NdFeB			
<b>Rated values for continuous operation</b>						
30	Rated torque	$M_N$	5,1	5	5	mNm
31	Rated current (thermal limit)	$I_N$	0,95	0,45	0,22	A
32	Rated speed	$n_N$	2 600	2 500	2 500	rpm

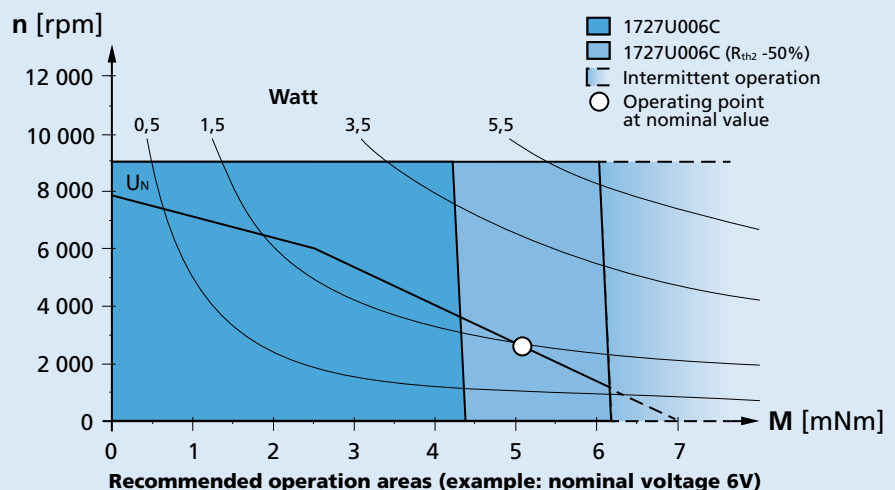
**Note:** Rated values are calculated with nominal voltage and at a 22°C ambient temperature. The  $R_{th2}$  value has been reduced by 25%.

### Note:

The diagram indicates the recommended speed in relation to the available torque at the output shaft for a given ambient temperature of 22°C.

The diagram shows the motor in a completely insulated as well as thermally coupled condition ( $R_{th2}$  50% reduced).

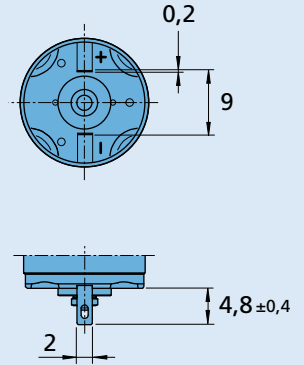
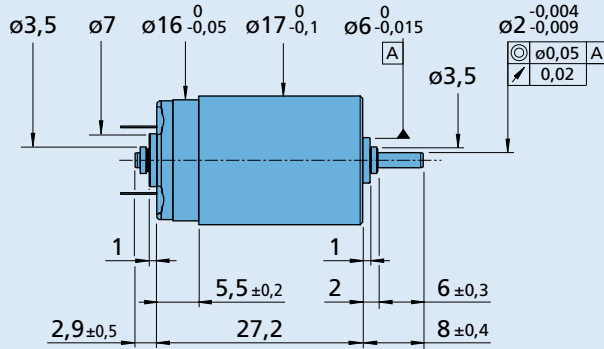
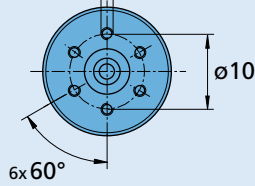
The nominal voltage ( $U_N$ ) curve shows the operating point at nominal voltage in the insulated and thermally coupled condition. Any points of operation above the curve at nominal voltage will require a higher operating voltage. Any points below the nominal voltage curve will require less voltage.



**Dimensional drawing**

Orientation with respect to motor terminals not defined

6x  $\begin{matrix} \oplus \\ \ominus \end{matrix} \begin{matrix} \text{Ø}0,3 \\ \text{A} \end{matrix}$  M1,6 2,5 deep



**1727 U ... C**